## $\mathcal{NC}$ and $\mathcal{P}$ -Completeness

## Nick's Class

 $\mathcal{NC}$ , or Nick's Class, is named after Nick Pippenger, currently on the faculty of Harvey Mudd College. A language is  $\mathcal{NC}$  if its membership problem can be solved by a parallel program using polynomially many processors in polylogarithmic time.

Many of the problems that you are familiar with are in the class  $\mathcal{NC}$ . For example, the 0/1 version of the shortest path problem is in  $\mathcal{NC}$ , and every context-free language is in the class  $\mathcal{NC}$ . Whether  $\mathcal{NC} = \mathcal{P}$  is an open question of enormous importance.

We say that a  $\mathcal{P}$ -TIME language (problem) is  $\mathcal{P}$ -complete if every  $\mathcal{P}$ -TIME language can be reduced to it by a function which can be computed in polylogarithmic time by polynomially many processors.

## The Circuit Value Problem, or the Boolean Circuit Problem

We now give a  $\mathcal{P}$ -complete problem, namely the circuit value problem. An instance of the Circuit Value Problem is a sequence of n Boolean assignments.

- 1. The left side of the  $i^{\text{th}}$  assignment is the Boolean variable  $x_i$ .
- 2. The right side of the  $i^{\text{th}}$  assignment is one of the following.
  - (a) 0 (false)
  - (b) 1 (true)
  - (c)  $x_j$  for j < i
  - (d)  $!x_j$  for j < i (! means 'not')
  - (e)  $x_i + x_k$  for j < i and k < i (+ means 'or')
  - (f)  $x_j * x_k$  for j < i and k < i (\* means 'and')
- 3. The answer to an instance of CVP is the value of  $x_n$ .

Trivially, CVP is in  $\mathcal{P}$ . Simply execute the *n* statements in order. In fact, the CVP is a Dynamic Programming problem. It is known that CVP is  $\mathcal{P}$ -complete, which implies that if it is in Nick's Class, then  $\mathcal{NC} = \mathcal{P}$ . Can we reduce every DP problem to the CVP, using a Nick's Class reduction?

## **Boolean Dynamic Programming**

We define a Boolean dynamic program  $\mathcal{P}$  to be a dynamic program for which the answer to every subproblem is a Boolean value. The *value* of  $\mathcal{P}$  is defined to be the value of  $x_n$ , the last subproblem. Let  $x_i$  be the value of the  $i^{\text{th}}$  subproblem of a Boolean dynamic program. Then there is a Boolean function of several variables  $F_i$  such that  $x_i = F_i(x_1, x_2, \dots, x_{i-1})$ . (Note that  $F_1$  is a function of no variables, hence is either constant 0 or constant 1.)

We define the *reachback* of a Boolean dynamic program to be the maximum integer d such that, for all i,  $x_i$  depends only on  $\{x_j : j \ge i - d\}$ .<sup>1</sup>

We define a *Boolean Dynamic Programming Language* to be any set of Boolean dynamic programs whose values are all **true**. For example, CVP is a Boolean dynamic programming language.

<sup>&</sup>lt;sup>1</sup>The reachback is an upper bound on the *width* of  $\mathcal{P}$ , as defined in the file dpNC01.

**Theorem 1** Given constants  $K, K_2$ , let  $DP[K, K_2]$  be the set of all Boolean dynamic programming problems whose values are true and whose reachback is bounded by  $K \log_2 n + K_2$ , where n is the length of the problem. then  $DP[K, K_2]$  is  $\mathcal{NC}$ .

**Theorem 2** The class of regular languages is  $\mathcal{NC}$ .

*Proof:* Let L be a regular language. Without loss of generality, L is over the Boolean alphabet  $\Sigma = \{0, 1\}$ . Let M be a DFA which decides L, and whose states are  $Q = \{q_0, q_1, \dots, q_{m-1}\}$ .

We define a reduction R from L to DP[0, 2m]. For  $w \in \Sigma^*$  Let  $\ell = |w|$ . R(w) is the Boolean dynamic program  $\mathcal{P}$  whose subproblems are  $x_i$  for  $0 \leq i \leq n = \ell m$ . We now define each subproblem. If i < n, let k = i % m and let t = i/m, integer trucated division. Then  $x_i$  is true if and only if the computation of M after t steps is in state  $q_k$ . We define  $x_n$  to be true if and only if the computation is in a final state after  $\ell$  steps. Clearly  $x_0$  is true, and the reachback of  $\mathcal{P}$  cannot exceed 2m, since the state of M at step t can be computed from the state of M at step t - 1, and  $x_n$  is true if and only if  $w \in L$ . R can be computed by  $\ell$  processors in  $O(m^2)$  time, hence the reduction is  $\mathcal{NC}$ .  $\Box$