## $NC$  and P-Completeness

## Nick's Class

 $NC$ , or Nick's Class, is named after Nick Pippenger, currently on the faculty of Harvey Mudd College. A language is  $\mathcal{NC}$  if its membership problem can be solved by a parallel program using polynomially many processors in polylogarithmic time.

Many of the problems that you are familiar with are in the class  $N\mathcal{C}$ . For example, the  $0/1$ version of the shortest path problem is in  $\mathcal{NC}$ , and every context-free language is in the class  $\mathcal{NC}$ . Whether  $\mathcal{NC} = \mathcal{P}$  is an open question of enormous importance.

We say that a  $\mathcal{P}\text{-}\text{TIME}$  language (problem) is  $\mathcal{P}\text{-}\text{complete}$  if every  $\mathcal{P}\text{-}\text{TIME}$  language can be reduced to it by a function which can be computed in polylogarithmic time by polynomially many processors.

## The Circuit Value Problem, or the Boolean Circuit Problem

We now give a P-complete problem, namely the circuit value problem. An instance of the Circuit Value Problem is a sequence of  $n$  Boolean assignments.

- 1. The left side of the  $i^{\text{th}}$  assignment is the Boolean variable  $x_i$ .
- 2. The right side of the  $i<sup>th</sup>$  assignment is one of the following.
	- (a) 0 (false)
	- (b) 1 (true)
	- (c)  $x_j$  for  $j < i$
	- (d)  $x_i$  for  $j < i$  (! means 'not')
	- (e)  $x_i + x_k$  for  $j < i$  and  $k < i$  (+ means 'or')
	- (f)  $x_i * x_k$  for  $j < i$  and  $k < i$  (\* means 'and')
- 3. The answer to an instance of CVP is the value of  $x_n$ .

Trivially, CVP is in  $\mathcal{P}$ . Simply execute the *n* statements in order. In fact, the CVP is a Dynamic Programming problem. It is known that CVP is  $P$ -complete, which implies that if it is in Nick's Class, then  $\mathcal{NC} = \mathcal{P}$ . Can we reduce every DP problem to the CVP, using a Nick's Class reduction?

## Boolean Dynamic Programming

We define a Boolean dynamic program  $P$  to be a dynamic program for which the answer to every subproblem is a Boolean value. The *value* of  $P$  is defined to be the value of  $x_n$ , the last subproblem. Let  $x_i$  be the value of the i<sup>th</sup> subproblem of a Boolean dynamic program. Then there is a Boolean function of several variables  $F_i$  such that  $x_i = F_i(x_1, x_2, \ldots, x_{i-1})$ . (Note that  $F_1$  is a function of no variables, hence is either constant 0 or constant 1.)

We define the *reachback* of a Boolean dynamic program to be the maximum integer d such that, for all *i*,  $x_i$  depends only on  $\{x_j : j \ge i - d\}$ <sup>1</sup>

We define a *Boolean Dynamic Programming Language* to be any set of Boolean dynamic programs whose values are all true. For example, CVP is a Boolean dynamic programming language.

<sup>&</sup>lt;sup>1</sup>The reachback is an upper bound on the *width* of  $P$ , as defined in the file dpNC01.

**Theorem 1** *Given constants*  $K, K_2$ , let  $DP[K, K_2]$  *be the set of all Boolean dynamic programming* problems whose values are true and whose reachback is bounded by  $K \log_2 n + K_2$ , where n is the *length of the problem. then*  $DP[K, K_2]$  *is*  $NC$ *.* 

**Theorem 2** *The class of regular languages is*  $NC$ *.* 

*Proof:* Let L be a regular language. Without loss of generality, L is over the Boolean alphabet  $\Sigma = \{0, 1\}$ . Let M be a DFA which decides L, and whose states are  $Q = \{q_0, q_1, \ldots q_{m-1}\}.$ 

We define a reduction R from L to  $DP[0, 2m]$ . For  $w \in \Sigma^*$  Let  $\ell = |w|$ .  $R(w)$  is the Boolean dynamic program  $P$  whose subproblems are  $x_i$  for  $0 \le i \le n = \ell m$ . We now define each subproblem. If  $i < n$ , let  $k = i\%m$  and let  $t = i/m$ , integer trucated division. Then  $x_i$  is true if and only if the computation of M after t steps is in state  $q_k$ . We define  $x_n$  to be true if and only if the computation is in a final state after  $\ell$  steps. Clearly  $x_0$  is true, and the reachback of  $\mathcal P$  cannot exceed  $2m$ , since the state of M at step t can be computed from the state of M at step  $t-1$ , and  $x_n$  is true if and only if  $w \in L$ . R can be computed by  $\ell$  processors in  $O(m^2)$  time, hence the reduction is  $\mathcal{NC}$ .  $\Box$